

Form PTO 1449 (Modified)		U.S. DEPARTMENT OF COMMERCE PATENT AND TRADEMARK OFFICE		ATTY DOCKET NO. 244370US2DIV		SERIAL NO. 10/691,642 New DIV Application	
LIST OF REFERENCES CITED BY APPLICANT				APPLICANT Katsuhiro MAEDA			
				FILING DATE Herewith		GROUP 3661 Not Yet Assigned	
U.S. PATENT DOCUMENTS							
EXAMINER INITIAL		DOCUMENT NUMBER	DATE	NAME	CLASS	SUB CLASS	FILING DATE IF APPROPRIATE
m.m.	AA	5,021,064	06/1991	Caines, R. Scott			
	AB	5,245,885	09/1993	Robertson, Glen A.			
	AC	5,871,386	02/1999	Bart, et al.			
	AD	6,066,026	05/2000	Bart, et al.			
	AE	6,439,508	08/2002	Taylor, Thomas C.			
	AF	6,450,104	09/2002	Grant, et al.			
	AG	5,351,602	10/1994	Monroe, John W.			
	AH						
	AI						
	AJ						
	AK						
	AL						
	AM						
	AN						
FOREIGN PATENT DOCUMENTS							
		DOCUMENT NUMBER	DATE	COUNTRY	TRANSLATION YES NO		
	AO	2001-96482	4/10/01	Japan (w/English Abstract)			x
	AP						
	AQ						
	AR						
	AS						
	AT						
	AU						
	AV						
OTHER REFERENCES (Including Author, Title, Date, Pertinent Pages, etc.)							
m.m.	AW	Masayuki INABA, et al., "Development of a Remote-Brained Robot with Two Legs and Two Arms", PROCEEDINGS OF THE 11 TH ANNUAL CONFERENCE OF THE ROBOTICS SOCIETY OF JAPAN, November 1993, pgs. 623-624					
m.m.	AX	Mills, Hybrid actuation of robotic manipulators: An Integral manifold control approach, 1990, IEEE, pp. 817-823					
m.m.	AY	Mills, Hybrid actuation for robot manipulators: Design, control and performance, 1990, IEEE, pp. 1872-1878					
	AZ					<input type="checkbox"/> Additional References sheet(s) attached	
Examiner McDowell Marc					Date Considered 12-22-04		
*Examiner: Initial if reference is considered, whether or not citation is in conformance with MPEP 609; Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.							